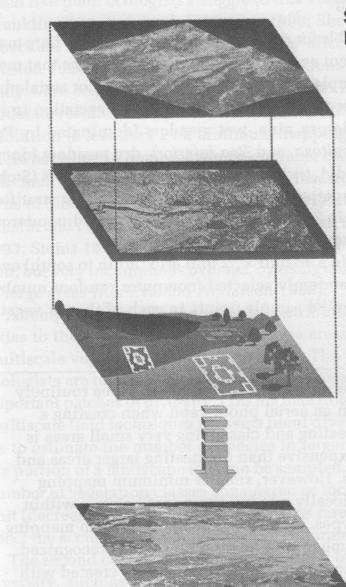
New technologies and options for future research at the Green Belt of Fennoscandia

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Contents

- Introduction
- New technologies
- Some examples
 - Resolution does matter
 - Kesonsuo mire
- Conclusions

Multi-phase and multi-scale sampling



Satellite Imagery for broad-scale extrapolation

High Resolution Aerial Photographs with common and rare habitats stratified

Field Sampling subset of random plots selected in common and rare habitats for long-term monitoring

GIS Based Predictive Model links to causal mechanisms

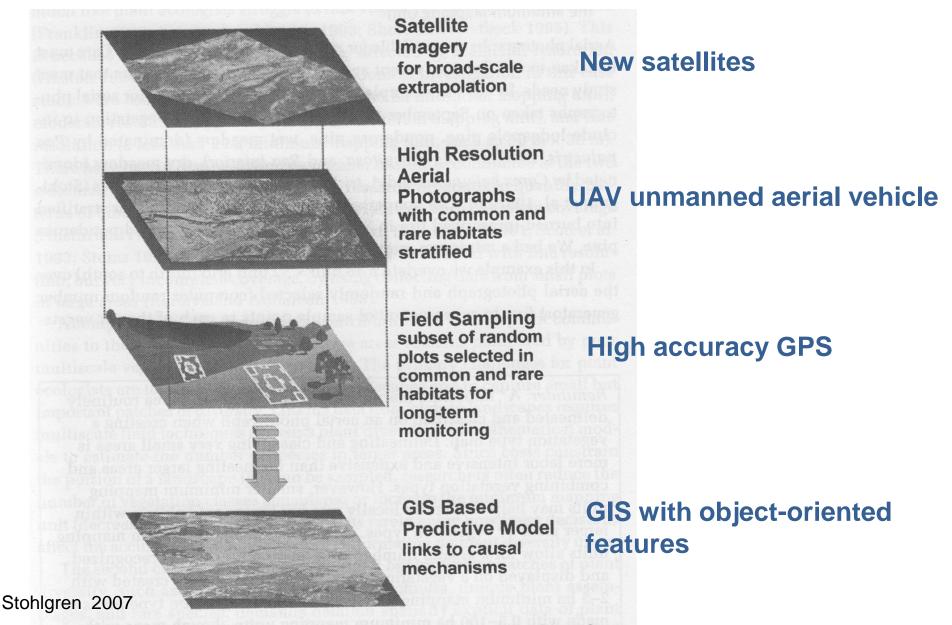
Stohlgren 2007

Multiscale biodiversity assessment

- 150 250 m (MERIS, MODIS) whole region
- 6 15 m (Landsat, ASTER, IRS) whole regior
- 0,6 2 m (QuickBird, IKONOS) subsets
- 10 25 cm (aerial images) subsets

What we are loosing or gaining from the image resolution?

Multi-phase and multi-scale sampling



UAV at Mekrijärvi Research Station



Electra Glider: Fiberglass

Length = 130 cm, Wing Span = 250 cm Weight = 3 kg, Electric Flight duration = up to 55 minutes Max speed = 60 km/h

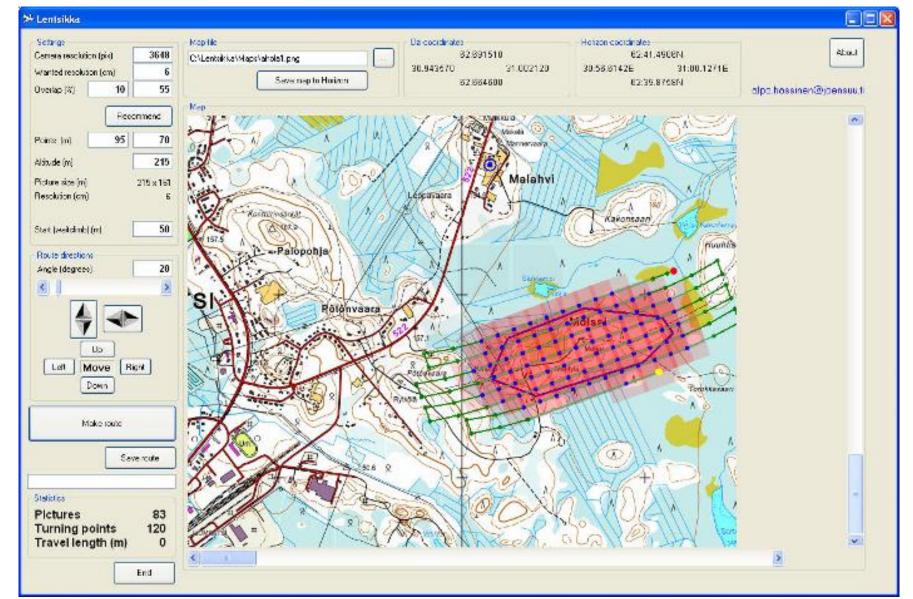
2 calibrated cameras = (digital camera, IR camera)



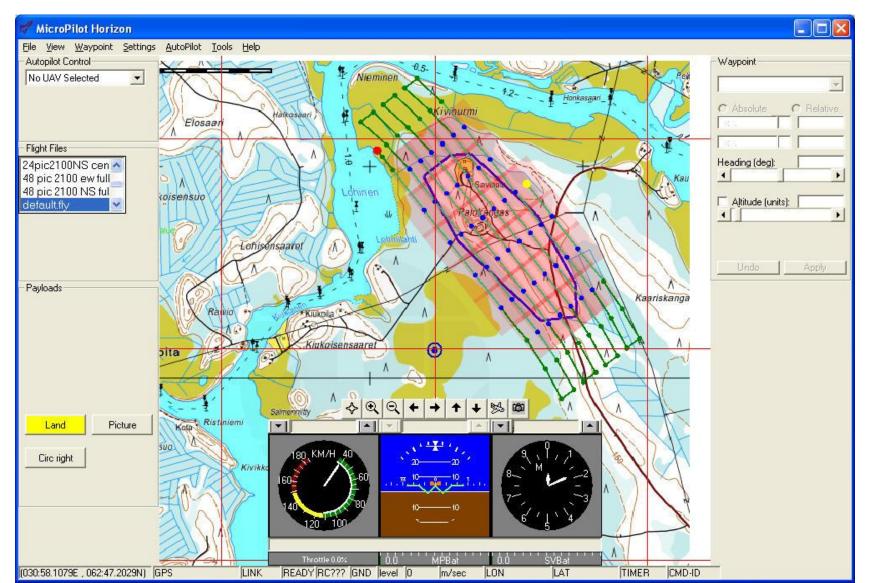
UAV Advantages

- High resolution images
- Geo-referenced
- On demand, not archived
- No cloud cover or satellite delay

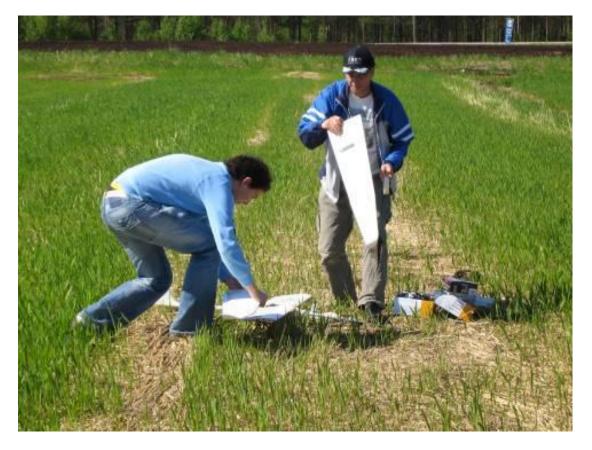
1. To create flight program



2. To transfer flight file to the ground control software



3. To send UAV to the air



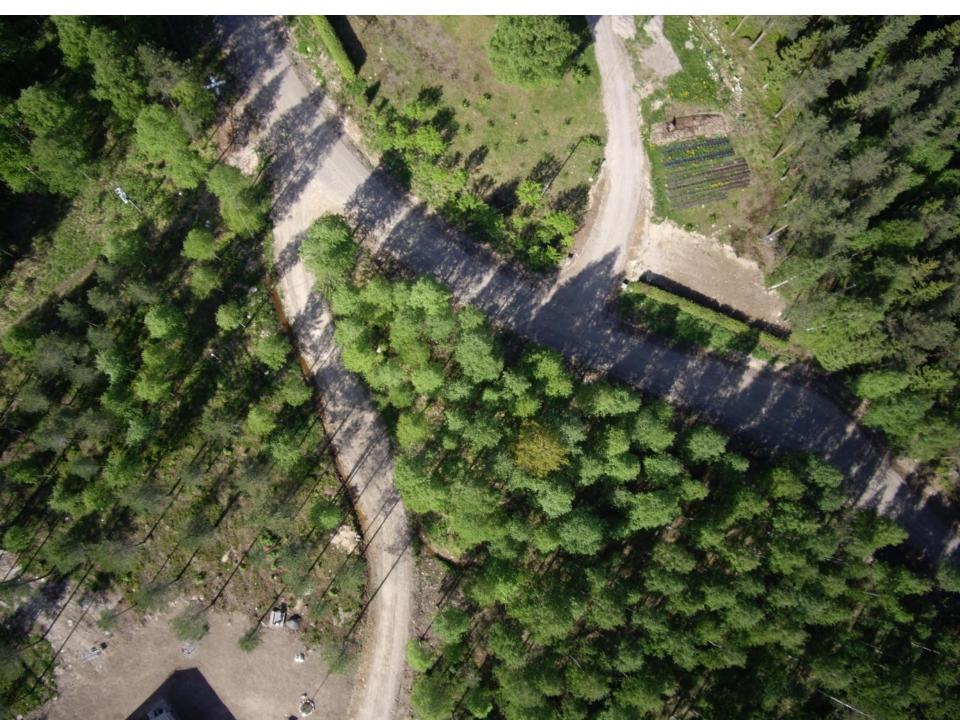


5. To process the log file and images

Current Pitch (rad x 1024)	328	cState	222
Current Roll (rad x 1024)	245	corrRoll	27
dP- Altitude	-16800	corrPitch	459
yDot Accelometer	10	GPS altitude (m)	445
dRoll	-174	GPS velocity (up / down)	31
GPS Heading (deg x 10)	2275	x- accelerometer	29
Location E (ft x 8)	-6031	Compass	0
Location N (ft x 8)	1715	Yaw	-2139
dPitch	354	desired heading	81
GPS Speed (ft/sec)	69	Heading control PID	20
AGL (Not in CropCam)	0	Climb state	5
GPS status	8192	Correction pitch dot	0
Temperature	19	Correction yaw dot	19
GPS pos E	31,02177	Body pitch dot	1136
GPS pos N	62,76311	Body roll dot	-15600
Air speed (ft/sec)	57	Body yaw dot	5472
Target speed (ft/sec)	47	Target heading (deg)	81
Current Altitude (ft x -8)	-8558	Event	-238

6. To mosaic the images and/or image run object-oriented image processing



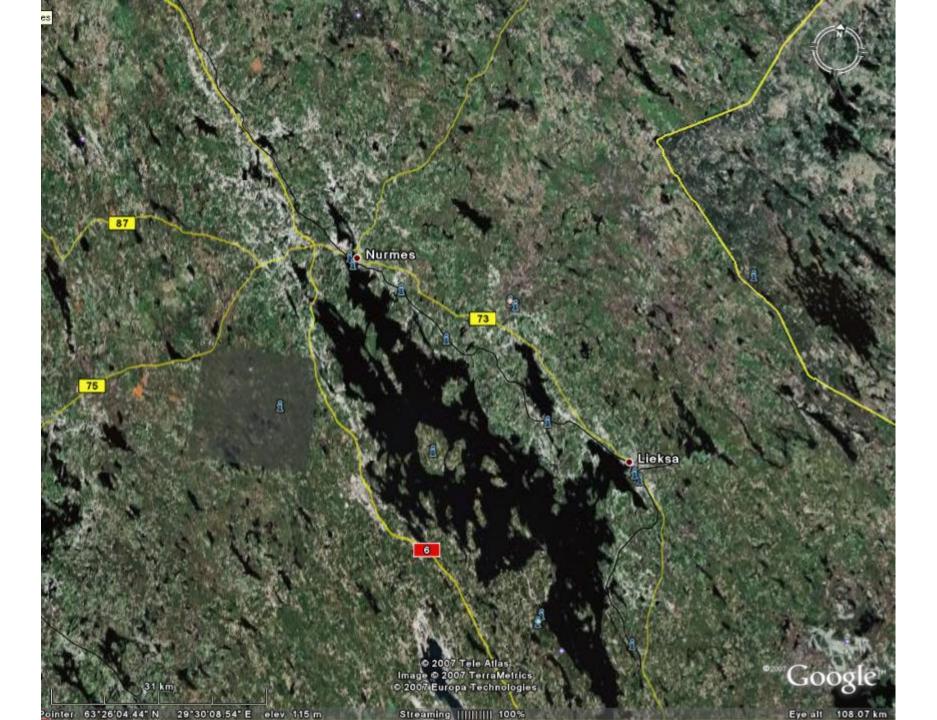


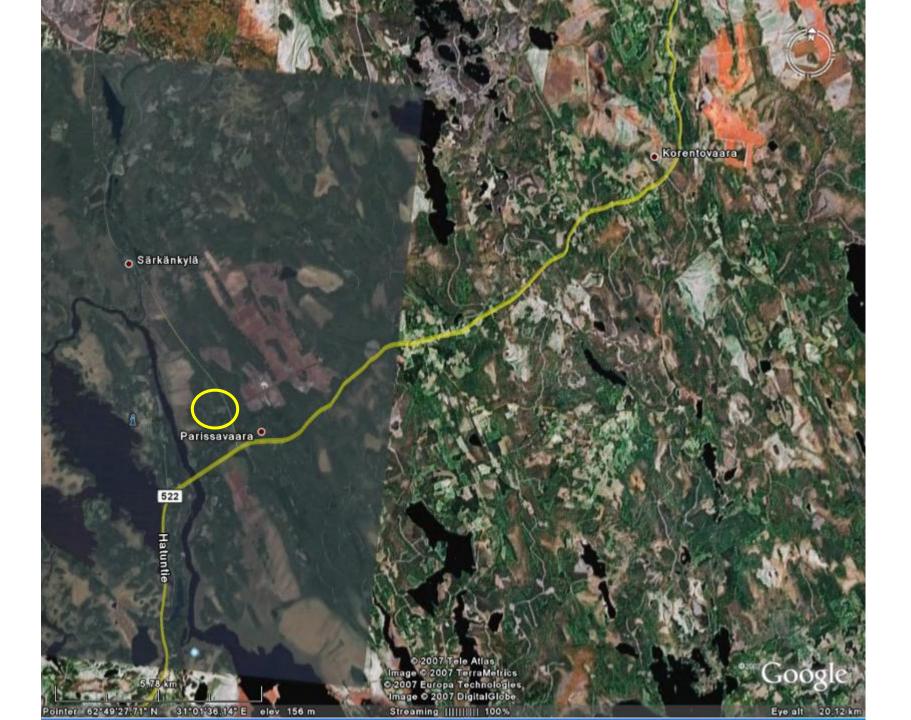






Resolution does matter!







QuickBird, 69 cm/pixel

1:755

QuickBird, 69 cm/pixel, IR

UAV



mark the plots with visible from the air markers

To make the full biodiversity inventory (species lists with coverages: plants, mosses, liverworts, lichens, mushrooms)

The

GPS coordinates of the plots (50 x 50 cm), postprocessing acuracy 50 cm

lo m

Additional information from UAV data

- Tree-wise inventory
- Age class of the individual trees (clear separation between old and medium-aged trees)
- Gaps structure
- Undergrowth
- Big species (ex. Vaccinium myrtillus)





eCognition Forester



<section-header>

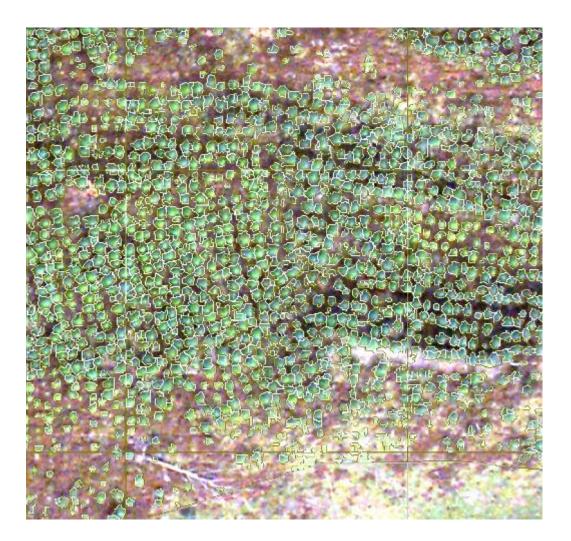
Subsets of ortho-photo

Classification result

Exported tree position

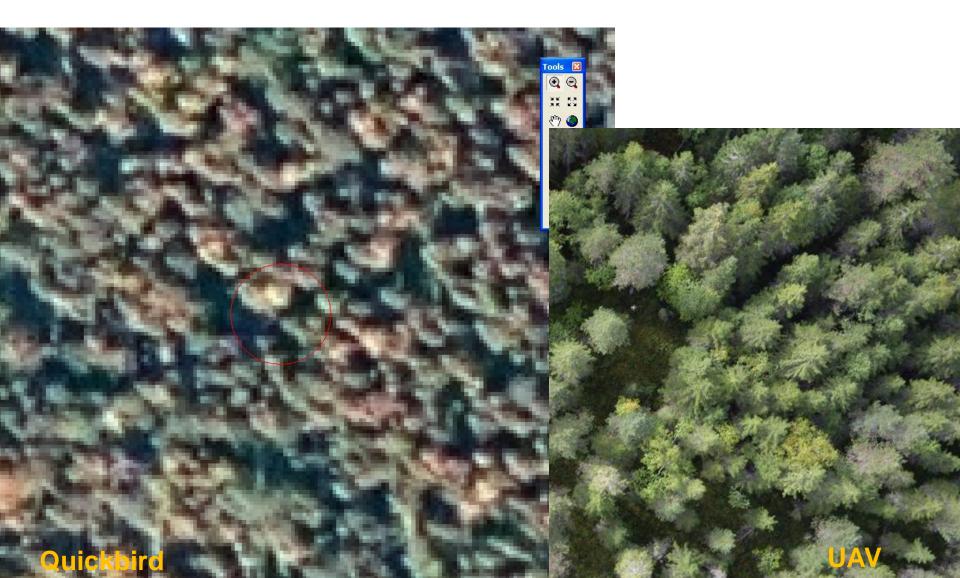
Transfer of rule base to ortho-photos of different areas with appropriate additional thematic layers.

Classification of single trees





Gap structure in forest



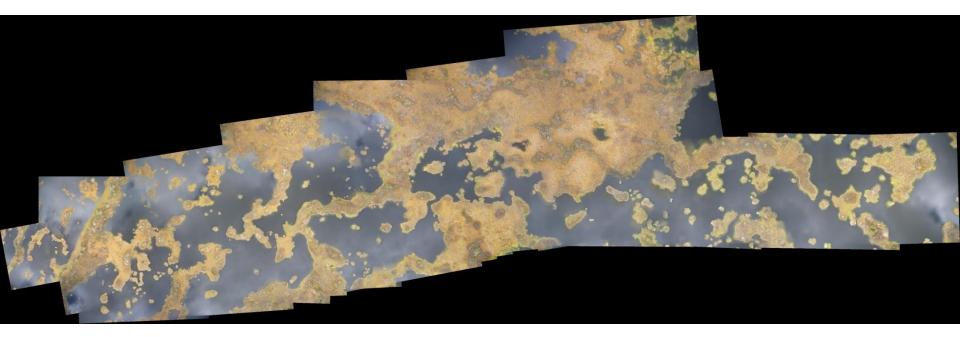
Example 2

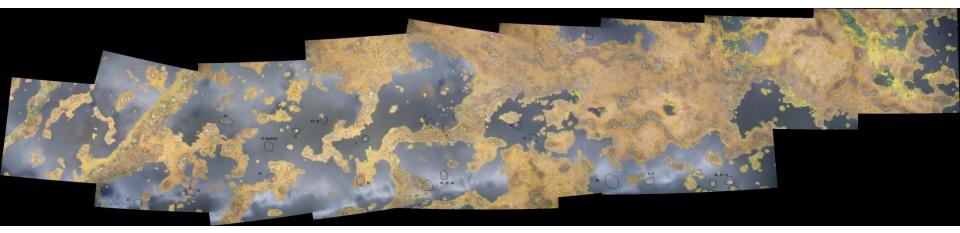
- Herring gull population living in Kesonsuomire (in Ilomantsi close to Mekrijärvi)
 - Small population
 - Eating in dumping ground of Joensuu (50 km)
 - Main questions:
 - Number of gulls
 - Number of nests
 - In co-operation with Risto Juvaste



Quickbird image

Kesonsuo-mire in Ilomantsi

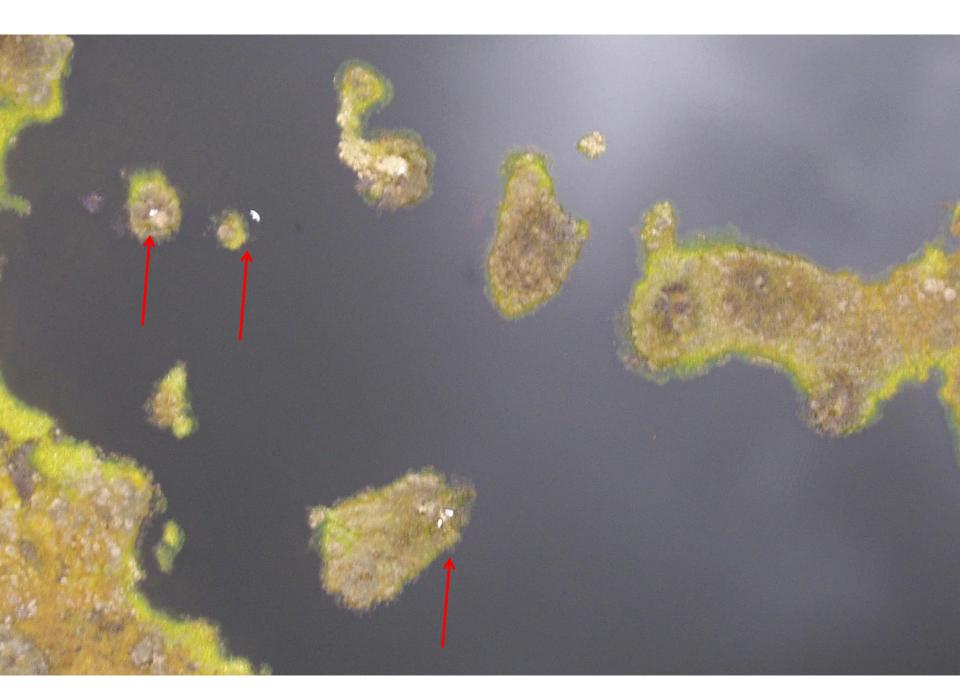












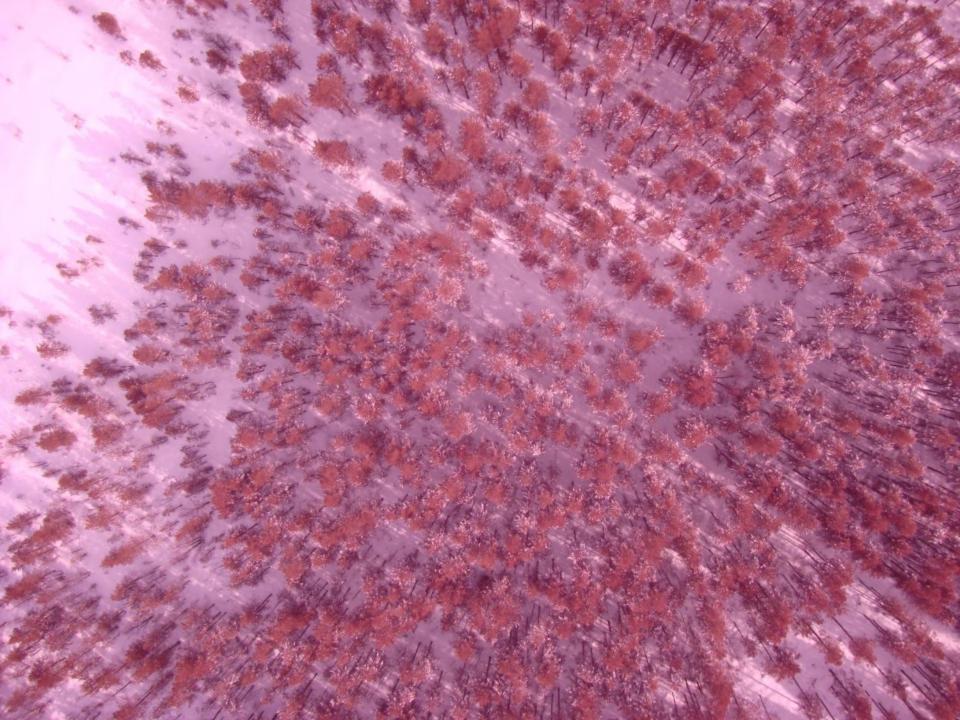
Other possibilities

- Lakes
- Winter images
- IR-images









Conclusions

- New techniques give a lot of new possibilities in remote sensing --- development is rapid.
- We do need the ground-truth data.
- Are we open and capable to utilise all the new possibilites available in near future?