# American options with guarantee

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# Outline



2 Diffusions as a driving process

Models with jumps



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Diffusions as a driving process

- 3 Models with jumps
- 4 Conclusion

### Problem

#### Options with guarantee

#### Guarantee a payoff that is a fraction of the starting value

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#### Options with guarantee

Guarantee a payoff that is a fraction of the starting value, i.e. payoff

 $g(X_{\tau}) \vee h(X_0)$ 

g: gain function, h: guarantee function g, h increasing,  $h \leq g$ 

$$v(x) = \sup_{\tau} E_x(e^{-r\tau} g(X_{\tau}) \qquad \qquad 1_{\{\tau < \infty\}}), \quad x \in E$$

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- Structure of the optimal strategies?
- Explicit determination?

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$$\psi_{+}(x) = \begin{cases} E_{x}(e^{-r\tau_{a}}\mathbf{1}_{\{\tau_{a}<\infty\}}), & x \leq a\\ [E_{a}(e^{-r\tau_{x}}\mathbf{1}_{\{\tau_{x}<\infty\}})]^{-1}, & x > a \end{cases}$$

and

$$\psi_{-}(x) = \begin{cases} [E_{a}(e^{-r\tau_{x}}\mathbf{1}_{\{\tau_{x}<\infty\}})]^{-1}, & x \leq a\\ E_{x}(e^{-r\tau_{a}}\mathbf{1}_{\{\tau_{a}<\infty\}}), & x > a \end{cases}$$

for a fixed point  $a \in int(I)$ .

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for a fixed point  $a \in int(I)$ .  $\psi_+$  resp.  $\psi_-$  are the (up to a factor) unique increasing resp. decreasing solutions to

$$(A-r)\psi=0$$

and each solution  $\psi$  can be written as  $\psi = \lambda_1 \psi_+ + \lambda_2 \psi_-$  for some  $\lambda_1, \lambda_2 \ge 0.$ 

Basic tool for problems without guarantee (C., I. 2010):

The optimal stopping set for

$$v(x) = \sup_{\tau} E_x(e^{-r\tau} \tilde{g}(X_{\tau}) \mathbb{1}_{\{\tau < \infty\}})$$

is given by the maximum points of

$$rac{ ilde{g}}{\lambda\psi_++(1-\lambda)\psi_-}, \qquad \lambda\in [0,1].$$

#### Corollary

Let  $x \in I$  and assume there exist  $y_1 \leq x \leq y_2$  and  $\lambda_1, \lambda_2 \in [0, 1]$  such that

$$y_i = argmax rac{ ilde{g}}{\lambda_i \psi_+ + (1 - \lambda_i) \psi_-} \qquad ext{for } i = 1, 2.$$

Then there exist  $x_1 \leq x \leq x_2$  such that  $v(x) = E_x(e^{-r\tau}\tilde{g}(X_{\tau}))$ , where

$$\tau = \inf\{t \ge 0 : X_t \le x_1 \text{ or } X_t \ge x_2\}.$$

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*Proof (Corollary):* By the basic tool  $y_1$  and  $y_2$  are in the stopping set *S*. Hence

$$x_1 := \sup\{y \in S : y \le x\} \text{ and } x_2 := \inf\{y \in S : y \ge x\}$$

are in S too, i.e.  $\tau_S = \tau$  under  $P_x$  and since the interval  $[x_1, x_2]$  is compact the assertion holds.

#### Theorem

Consider the optimal stopping problem with guarantee

$$v(x) = \sup_{\tau} E_x(e^{-r\tau}[g(X_{\tau}) \lor h(X_0)] 1_{\{\tau < \infty\}}), \ x \in E.$$

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Assume  $\lim_{y\to b_r} \frac{g(y)}{\psi_+(y)} = 0.$ 

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Consider the optimal stopping problem with guarantee

$$v(x) = \sup_{\tau} E_x(e^{-r\tau}[g(X_{\tau}) \vee h(X_0)] \mathbb{1}_{\{\tau < \infty\}}), \ x \in E.$$

Assume  $\lim_{y\to b_r} \frac{g(y)}{\psi_+(y)} = 0$ . For each starting point x with h(x) > 0 there exist  $a_x \le x \le b_x$  such that

$$\tau_x^* = \inf\{t \ge 0 : X_t = a_x \text{ or } X_t = b_x\}$$

is optimal.

## Proof of the Theorem

It is easy to see that for  $\lambda$  near 1

$$\sup_{y \leq x} \frac{g(y) \lor h(x)}{\lambda \psi_+(y) + (1-\lambda)\psi_-(y)} > \sup_{y \geq x} \frac{g(y) \lor h(x)}{\lambda \psi_+(y) + (1-\lambda)\psi_-(y)}$$

Therefore by assumption on the boundary behavior there exist  $\tilde{a}_x \leq x$  and  $\lambda_1$  such that

$$ilde{\mathsf{a}}_{\mathsf{x}} = \operatorname{argmax}_{\mathsf{y}} rac{\mathsf{g}(\mathsf{y}) ee \mathsf{h}(\mathsf{x})}{\lambda_1 \psi_+(\mathsf{y}) + (1-\lambda_1) \psi_-(\mathsf{y})}.$$

The same argument for  $\lambda$  near 0 provides  $\tilde{b}_x \ge x$  with

$$ilde{b}_{\mathsf{x}} = \operatorname{argmax}_{y} rac{g(y) \lor h(x)}{\lambda_{2}\psi_{+}(y) + (1-\lambda_{2})\psi_{-}(y)}.$$

The assertions follows from the Corollary.

## Explicit determination of the optimal boundaries

Assume g(x) = h(x). Write

$$F(x, a, b) := E_x(e^{-r\tau_{a,b}}[g(X_{\tau_{a,b}}) \vee g(x)]1_{\{\tau_{a,b} < \infty\}}),$$

where  $\tau_{a,b} = \inf\{t \ge 0 : X_t = a \text{ or } X_t = b\}$ .  $(a_x, b_x)$  is maximum point of  $F(x, \cdot)$ .

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#### Reduction to ODE

$$\frac{d}{dx}(a_x, b_x) = -(D_{2,3}^2 F(x, a_x, b_x))^{-1} D_1 D_{2,3} F(x, a_x, b_x).$$

# Example: GBM-Stock with guarantee

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$$\tau_x^* = \inf\{t \ge 0 : ax \le X_t \text{ or } X_t \le bx\},$$
$$v(x) = cx.$$



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## Lévy processes

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Proposition

(i) For all  $x \in \mathbb{R}$  there exists  $a_x \in [-\infty, x]$  such that

$$S_{x} \cap (-\infty, x] = (-\infty, a_{x}].$$

(ii) For all  $x \in \mathbb{R}$  it holds that

$$S_x \cap [x,\infty) \neq \emptyset.$$

# Spectrally negative Lévy processes

For analytic tractability: X is spectrally negative, i.e. it has no upward jumps, h = g.

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#### Theorem

For each starting point x with h(x) > 0 there exist  $-\infty < a_x \le x \le b_x < \infty$  such that

$$\tau_x^* = \inf\{t \ge 0 : X_t \le a_x \text{ or } X_t = b_x\}$$

is optimal.

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### Thank you for your attention!